AN EXPERIMENTAL INVESTIGATION OF A LOW SPEED LONG LINEAR INDUCTION MOTOR DIVIDED INTO SEVERAL STATORS CONNECTED IN SERIES

إستقصاء معملى لمحرك إستنتاجى خطى بطئ السرعة عضو إستنتاجه الطويل
مقسّم إلى أعضاء عديدة متصلة معاً على التوالى

Dr. S. A. El-Drieny
Electrical Engineering Department,
Faculty of Engineering, El-Mansoura University,
El-Mansoura, Egypt

ملخص البحث :

تستلزم المحركات الإستنتاجية الخطية المستخدمة فى دفع القطارات الكهربائية ذات السرعة البطيئة بناء عضو الإستنتاج لتكون منفاته المغذاه بالتيار المتردد ذات عدد كبير من الأقطاب المغناطيسية وينشأ عن هذا طول غير عادى للقلب الحديدى الحامل للمنفات مما يسبب صعوبة بالغة فى تثبيته أسفل عربات القطار وأيضاً عدم إنتظام الثغرة الهوائية بينه وبين الجانب الثانوى من المحرك وللتغلب على هذة الصعوبات يتم بناء عضو الاستنتاج من عديد من الأعضاء تقتسم بالتساوى العدد الكلى من الأقطاب اللازمة للمحرك. يقدم هذا البحث دراسة معملية لتأثير تقسيم عضو الإستنتاج على أداء المحرك خاصة فى حالة حدوث عدم تشابه فى الأقطاب المتتابعة على طول الآلة بسبب توصيل خاطئ لملفات الأجزاء المختلفة المتصلة على التوالى. تحقيقاً لهذا الهدف تم بناء نموذج معملى يحمل الجزء الثابت فيه قلبا حديدياً لمنفات ثلاثية الوجه ذات ستة أقطاب ويمكن إستبداله بثلاث قلوب يحمل كل قلب منها منفات ثلاثية الوجه ذات قطبين ويمثل الجانب الثانوى قرص من الآلومنيوم ذو قطر مناسب لضمان سرعة تزامنية خطية ثابته. ولقد أثبتت التجارب المعملية أن أداء المحرك ذو القلب الحديدى الطويل أفضل من حيث قوة الدفع ومعامل القدرة والجودة نظراً لغياب تعدد تأثير النهايات" الموجودة فى القلب الحديدى المقسم. حيث يبدو تأثير ذلك واضحاً فى توزيع كثافة المجال المغناطيسى وتوضح القياسات إنخفاض القيمة المتوسطة لكثافة المجال المغناطيسى على طول الآلة خاصة فى حالة تقسيم القلب الحديدى ذو التتابع غير المتشابه للأقطاب والذى أعطى أقل قيم لقدرة الدفع والجودة ومعامل القدرة. والبحث يؤكد أهمية إستخدام القلب الحديدى المقسم على الرغم من الفارق الطفيف فى قيم الأداء بالمقارنة بالقلب الحديدى الطويل حيث يقدم حلاً للمشاكل والصعوبات الإنشائية الخاصة ببناء المحرك أسفل عربات القطار كما يشير البحث إلى ضرورة الإلتزام بالتتابع القطبى المتشابه فى حالة إستخدام القلب الحديدى المقسم وذلك للحصول على أفضل أداء.

ABSTRACT

An experimental study of a linear induction motor whose stator is divided into short stators that are connected in series is presented. The investigation includes a comparison of this motor with another motor having undivided stator. The present investigation is concerned with no-load and full-load conditions. the thrust, the power factor and the efficiency are reported under both constant current and voltage operations. Measurements of air gab flux over the length of the long stator and the three short divided stators are also presented. The cascade connection of three divided short stators for different distribution of phase m.m.f.: namely the same polarity distribution (N-S-N-S-N-S) and opposite polarity distribution is presented.

The experimental results recommended the cascade connection with the same distribution m.m.f.and a minimum distance between the stators to yield free movement and reduce the entry and exit ends power loss. The experimental study aims to demonstrate the divided short stator and to solve the problem regarding the suspension of long stator on the train to cope with steep slope and irregularities of the track.

1. INTRODUCTION :

Considerable interest has been developed in recent years in the use of linear induction motor as the propulsion for future high speed trains. The linear induction motor LIM provides simple and rigid structure. Because of the structural advantages, the LIM is considered as a suitable type of propulsion motor for both high and low speed trains [1-6]. However, this application requires a good technique for speed control and electrical braking due to frequent stops. In addition to some problems regarding the suspension of long primary on the train and difficulty to cope with steep slope and irregularities of the track. To solve the above problems a long stator LIM, divided into some short stators connected in series, is built in electrical engineering laboratory of El-Mansoura University , see figure (1) and picture (1). Experimental investigation is concentrated on the performance, the thrust, the efficiency, and the power-factor under constant current and voltage operations. Measurements of air-gap flux density over the length of stator under no-load is also presented. Also, the thrust is measured and compared in the two differences :the long stator divided into short ones, connecting in series, and long stator which is undivided (LIM-A). The experimental results are used to understanding the LIM of long stator divided into short ones connected in series under load for different distribution of phase m.m.f., either in the same polarity distribution (N-S-N-S), (LIM-B) , or in opposite polarity distribution of phase m.m.f. (N-S-S-N), (LIM-C) .

2. DESCRIPTION OF THE PROTOTYPE MOTOR :

A laboratory prototype motor is constructed to enable the detailed experimental studies. The model consists of two parts , see Fig.(1) ; a double-sided stator as the primary part ; and an aluminum rotating disc as the secondary part. The disc is made of 7 mm thickness and fixed on an axle which is free to rotate between two bearings. One stator side is wound for six poles and fitted in flat, 60 cm long , laminated core. The other side of stator is divided into 3 several ones fitted in flat . each 20 cm long and is wound for two poles, laminated core. Each stator is mounted in a rigid yoke assembly , and supported to a trapezoidal mild steel frame through two aluminum pieces ; to minimize the magnetic leakage from the stator core to the frame. The centre line of each stator is at radius of 20 cm from the disc axis. Each stator consists of 12 cm stack of 0.35 mm silicon steel laminations with an inorganic interlaminar coating. These laminations are supported together with two mild steel plates of 5 mm thick, one at each side. The three short divided stators (SDS) each has 16 open slots are cut by a milling machine into the face of the assembled core. While the long stator (LS) has 40 open slots. The windings for both SDS and LS are double layer with two slots per pole per phase.

The facility of adjusting the air-gap length had been considered. It is taken to be 14 mm between the two stator sides (SDS and LS) inclusive the thickness of an aluminum disc. The rotor disc diameter is chosen to be large compared with stator width. Accordingly, the

peripheral speed of the disc is determined by disc periphery tangential to the stator centre line. The synchronous speed is 10 m/sec at the centre of the stator, which corresponds to a pole pitch of 10 cm.

Numerical design example of long stator [5], and 3 divided short ones is shown in Table (1). LIM A is designed in a long stator structure (6-poles), LIM B and LIM C consists of 2-poles stator respectively, which are divided LIM A with 6-poles into three. The three divided short stators LIM B are connected in series and arranged in the same distribution of phase m.m.f. type (N-S-N-S-N-S). While the three divided short stators LIM C are connected in series and arranged in opposite polarity distribution of phase m.m.f. type (N-S-S-N-N-S).

3. EXPERIMENTAL RESULTS :

The tests for measuring the magnetic flux distribution along the 3-divided short stators for both m.m.f. arrangement (N-S-N-S) and (N-S-S-N) and the long stator are carried out under no load condition. Also the thrust , the efficiency and the power factor are measured under load condition in case of constant voltage and current operations for the above stators.

3.1. Magnetic Distribution Along The Stator Surface :

To measure the core flux along, a search coil of 10 turns is wound and fixed at the top of each tooth. The ends of the search coil are connected to the oscilloscope and the induced voltage can be measured. So, the flux which proportional to the induced voltage can be calculated. Figure (2) shows the flux distribution along the three short divided stators with the same polarity distribution of phase m.m.f. (LIM B) . Figure (3) shows the flux distribution along the undivided stator (Long one LIM A). Figure (4) shows the flux distribution with the opposite polarity distribution of phase m.m.f. (LIM C) . It can be noticed from the figures that the flux is weakened at the entry ends due to the entry end effects then it built up gradually. There are dips and sharp rises due to the discreet distribution of ampere turns in the slots and reflected exit-end wave. So, due to several entry and exit ends, the average flux distribution in case of three divided short stator with the same polarity distribution of phase m.m.f. is smaller than the average flux distribution in case of long stator and greater than the average flux distribution in case of three divided short stator with opposite polarity distribution of phase m.m.f..

3.2 Thrust and Efficiency :

Measurements of the thrust is carried out by using a calibrated spring on one side of an attached wheel to the axle of the disc rotor and balanced with weights on the other side of the wheel. Figure (5) shows the measured thrust per meter under constant current for long stator (LIM A), 3 SDS (LIM B) and 3 SDS (LIM C). Figure (6) shows the measured thrust per meter under constant voltage for (LIM A) , (LIM B) and (LIM C). It can be noticed that from the figures the maximum thrust developed in case of (LIM B) , three divided short stator with the same polarity distribution of phase m.m.f. is smaller than the maximum thrust developed in case of (LIM A) and greater than the maximum thrust developed in case of (LIM C) the opposite polarity distribution . Generally the maximum thrust developed in case of current source is higher than the maximum thrust developed in case of voltage source.

CONCLUSION :

Building and testing of both long stator LIM (A) with 6 poles and three short stators (each has 2-poles) has resulted in an under standing the overall behaviour and characteristics under no-load and load conditions. By use of this facility, the thrust , efficiency and air-gap flux along long stator and three divided short stators were investigated under constant current and voltage operations.

The laboratory prototype motor is sufficiently flexible to examine the cascade connection of the three divided short stators for different arrangement distribution of phase m.m.f., either in the same polarity distribution (N-S-N-S-N-S) or in opposite polarity distribution of phase m.m.f. (N-S-S-N-N-S).

The results show that undivided stator (Long Stator) gives high normal thrust by about 10% rather than the divided one. But the problem regarding the suspension of long stator on the train pushing the designers of such type of LIM prefer the undivided short stator regarding the reduction of the thrust by about 10% than the long stator. Attention must be considered on cascade connection of several short stators, because the experimental results give high thrust by 10% in case of the same polarity distribution rather than the opposite polarity distribution.

The experimental tests pointed out that high thrust can be obtained under constant current operation than under constant voltage operation. Generally the efficiency is too bad in case of several divided short stators due to several existence of entry and exit ends power less rather than of long stator.

The advantage of suspension of several short stators on the train to cope with steep slope and irregularities of track is essential for practical application regardless the reduction of the thrust or efficiency by 10%.

The reasonable distance between short stators to maintain the continues free movement and to reduce the entry and exit ends power loss is not to increase by about half the pole pitch.

REFERENCES :

[1] S. Nonaka and T. Higuchi. :"On the design of single-sided Linear Induction Motors for propulsion of Maglev Vehicles", Proc. of Tnt. Conf. on Maglev Transport' 85 pp 45-52 Sep. 85 .

[2] A. Odendahi and K. Sattler. :"The behaviour of series connection of two linear induction motors with predicted motor distances", Proc. of Int Conf. on Elect. Machine pp 125-135 . Sep. 1980 .

[3] S Nonaka and N. Fujii, :"Three dimensional analysis of high-speed Linear Induction Motor with finite iron dimension", Trans. IEE Japan No. 100-B, 7 pp 413-420, Jul 1990, Elect. Eng. Japan Vol 100, 4 pp 42-50 Jul./Aug. 1990 .

[4] S. Nonaka, K. Yoshida and K. Ogawa, :"Magnetic fields in high speed Linear Induction Motors taking into account finite length of primary cores", Proc. of Int. Conf. on Electrical Machine pp 76-83 September 1980 .

[5] S. A. EL-Drieny, :"An experimental investigation of a low speed
    double sided linear induction motor", Bulltin of Faculty of
    Engineering El-Mansoura University Vol. 11 , No.2 , December 1986 .

[6] M. Iwamoto, S. Sakaba, K. Kitagawa and G. Utsami, :"Experimental
    and theoretical study of high speed single sided linear induction
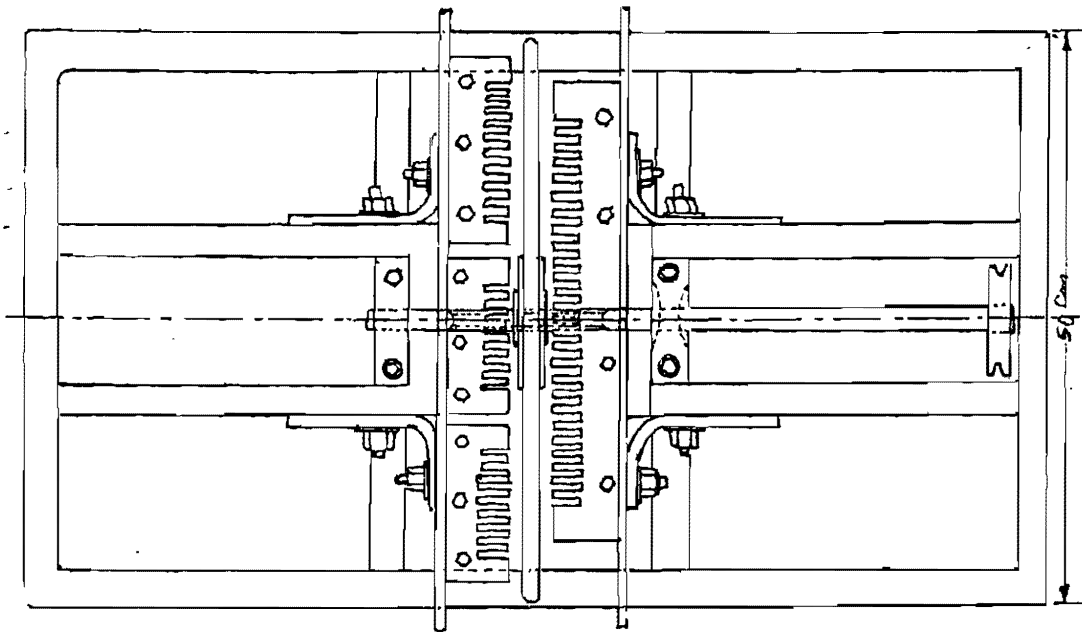   motors", IEE Proc. , Vol. 128 . No.6 , Nov. 1981 .

Fig. (1) : Construction of LIM Rig.

Table (1) : Design Example

P A R A M E T E R	Numerals	
	LIM (A)	LIM (B&C)
Number of poles per one LIM	2	2
Number of LIMS connecting in series	1	3
Primary core length per one LIM	67.98 cm	27.98 cm
Weight of copper per one LIM	11.20 Kg	5.70 Kg
Voltage per phase	220 V	220 V
Frequency	50 Hz	50 Hz
Synchronous speed	10 m/s	10 m/s
Thrust	493 Kg.m	493 Kg.m
Number of phases	3	3
Rated current	7.5 A	7.5 A
Pole pitch	100 mm	100 mm
Slot/pole/phase	2	2
Slot width	10 mm	10 mm
Tooth width	6.66 mm	6.66 mm
Stack height	78 mm	78 mm
Over hang length	51.5 mm	51.5 mm
Number of turns / coil	114	120
Core width	11.5 cm	12.6 cm
Winding	double layer 60 Deg.	double layer 60 Deg.
Phase spread		
Current Density	4 A/mm^2	4 A/mm^2
Winding factor	0.827	0.827
Cross section area of conductor	1.59 mm^2	1.59 mm^2
Paking factor	0.6	0.6
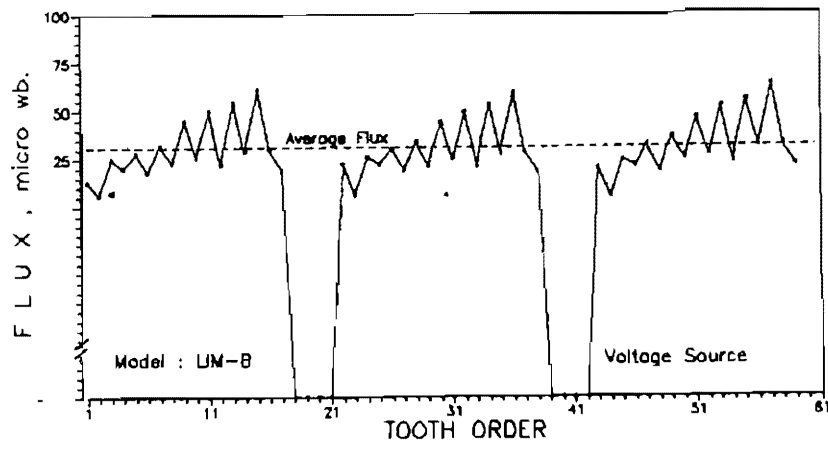
Fig.(2): Flux Distribution Along The 3 Short Divided
          Stators With The Same Polarity Distribution
          of Phase m.m.f. (LIM B) .
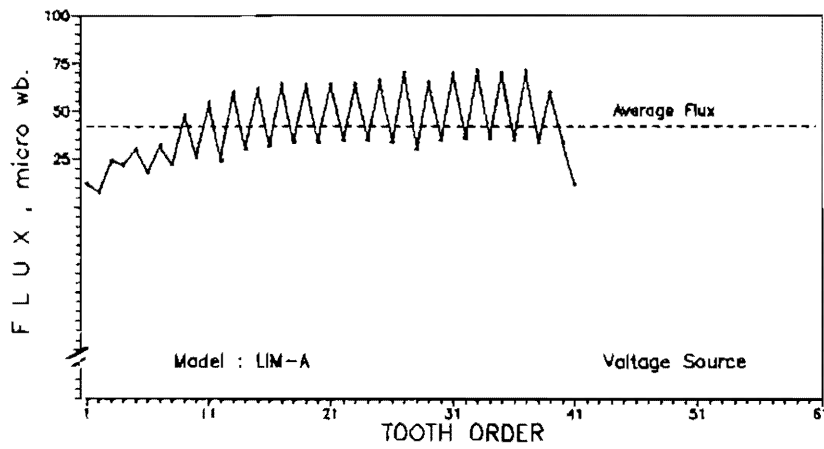
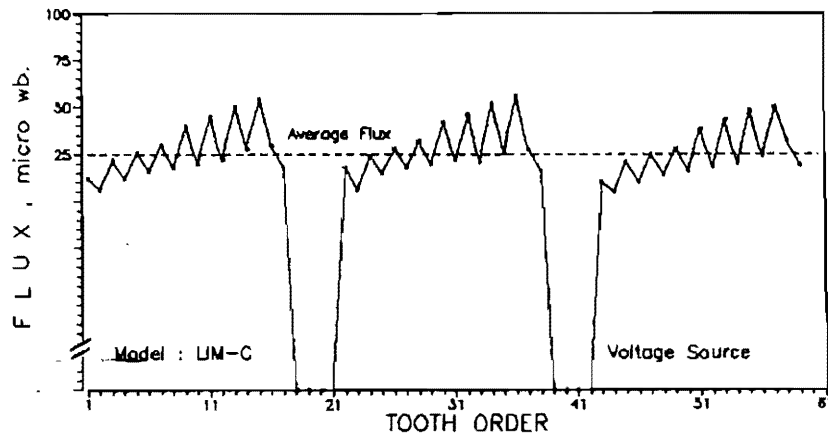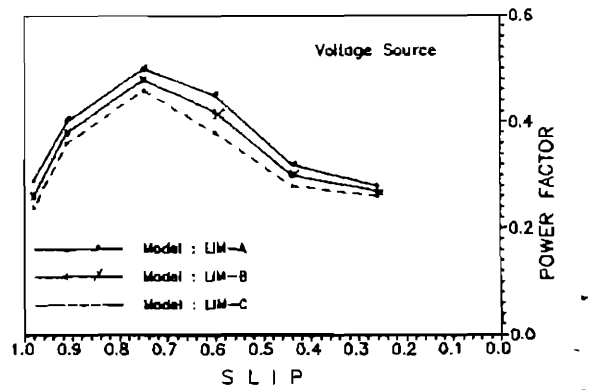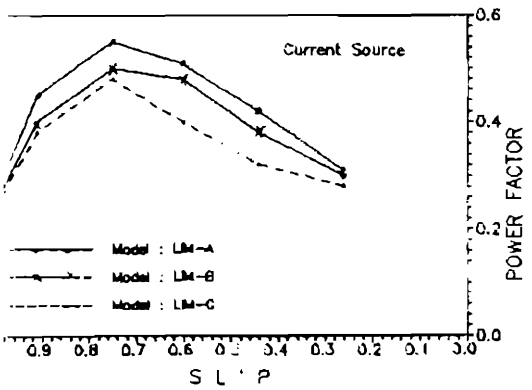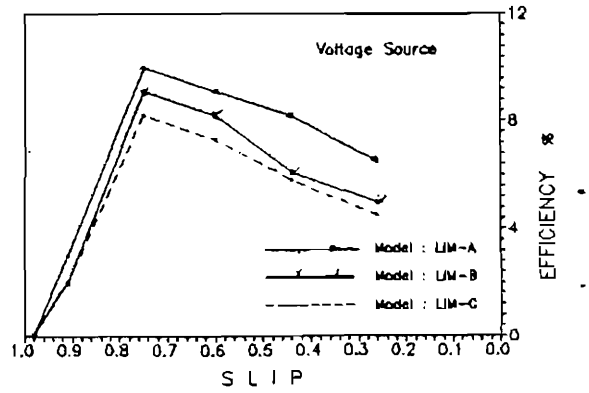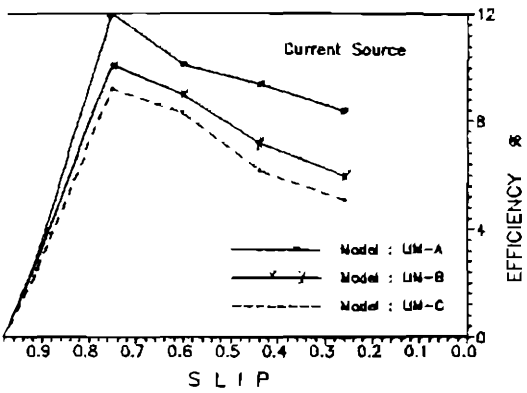Fig.(3): Flux Distribution Along The Undivided Stator (LIM A).
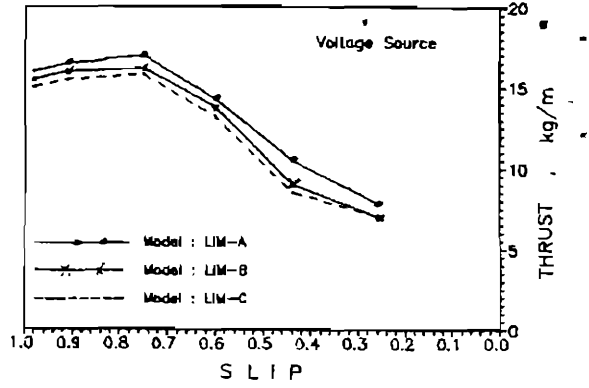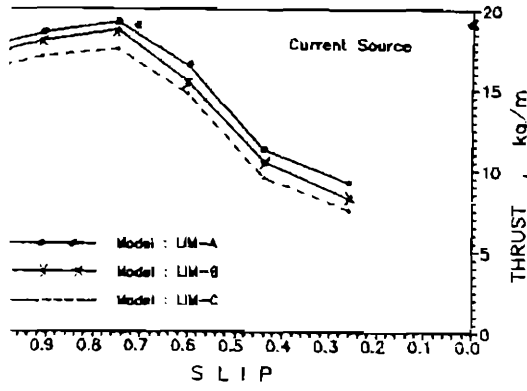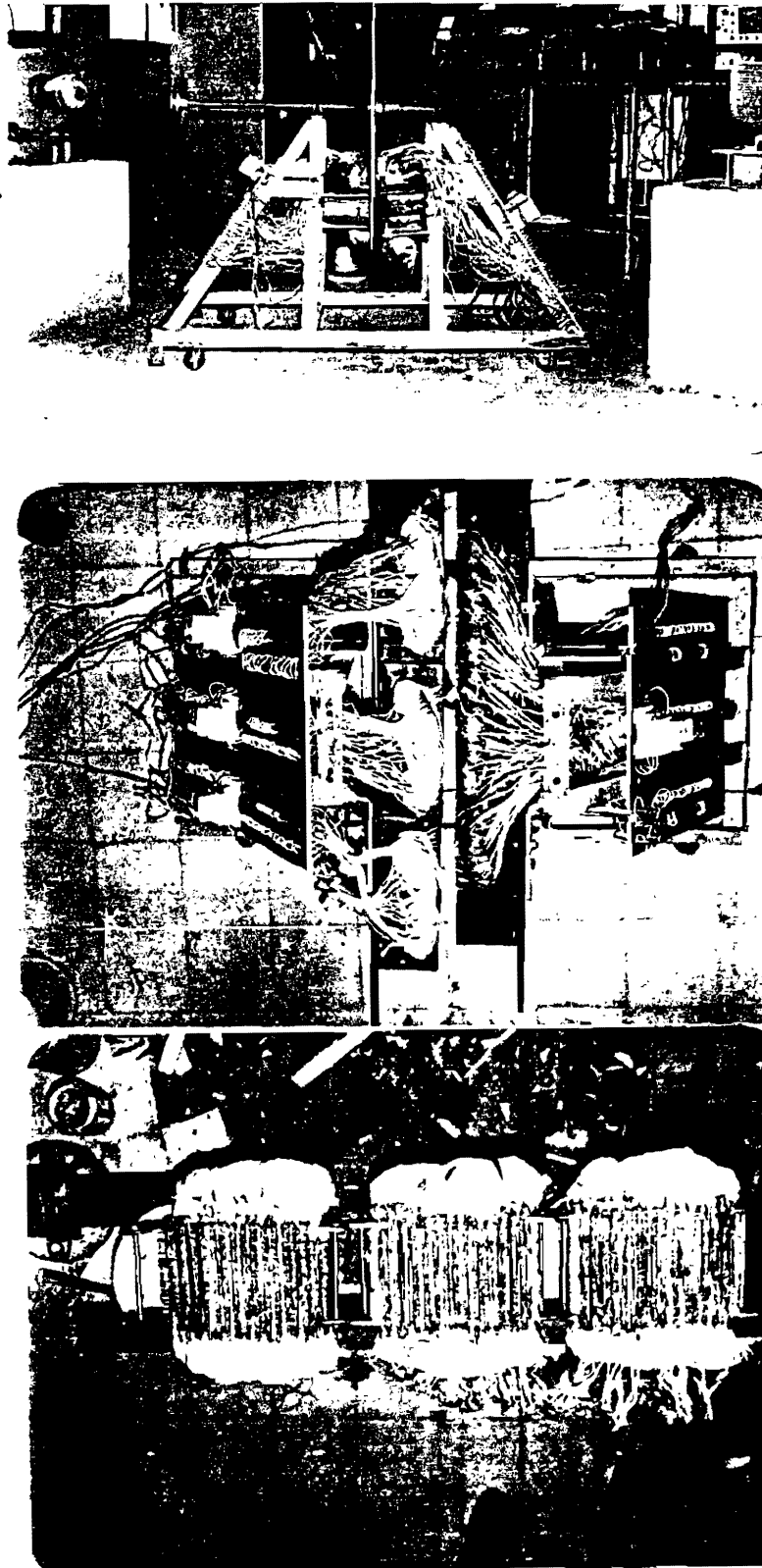

Fig.(4): Flux Distribution Along The 3 Short Divided
          Stators With The Opposite Polarity Distrib-

.(5): Measused Thrust/m. Efficien-
cy % and P.F. under Constant
Current For LIM A LIM B and
LIM C.

Fig.(6): Measused Thrust/m, Effici ·n-
cy % and P.F. under Const int
Voltage For LIM A, LIM B and
LIM C.

Picture (1) : The Laboratory LIM Prototype Motor.