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امتحان حسابات 2019

Faculty of Electronic Engineering Fourth Year Dept. of Computer Science & Engineering Time (3 hrs.): 10 am – 1 pm Instructor: Prof. Nabil Ismail		Subject: Elective 5 1 st Semester 2018/2019 Sunday 6/1/2019 No. of pages: 2 Total Marks: 70 Marks
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Answer as much as you can:

[1] [15 Marks]

i) Multiple choice questions (you must select only one choice):

- 1- To take advantages of the multicore CPUs/manycore GPUs you have to use:
 - a) Shared programs
 - b) distributed programs
 - c) multithreaded programs
- 2- A parallel program runs on a single multicore node uses
 - a) distributed memory
 - b) loosely coupled cores
 - c) shared memory
- 3- CUDA is well suited for implementing the parallel design model.
 - a) SISD
 - b) SIMD
 - c) SPMD

ii) Fill in the spaces:

- 1- Parallel programmers use a, or to write shared memory parallel programs
- 2- Parallel application dimensions taxonomy are, and
- 3- PCAM parallel solutions methodology stands for,,,, and
- 4- CNNs are the most representative supervised deep learning model. They consist of mainly 4 types of layers,,, and

iii) True/False you should state why?

- 1- A shared address space facilitates migration from a sequential programming model to a parallel one.
- 2- GPU cores best performance model is MIMD parallelism
- 3- OpenCL distinguishes between the devices (usually GPUs or CPUs) and the host (CPU).
- 4- Data-dependent branching will perform well on a GPU.

[2] [20 Marks]

- i) A sequential application with a 20% part that must be executed sequentially, is required to be accelerated three-fold. How many CPUs are required for this task? If the required speedup was 5, what would be the number of CPUs required?
- ii) A parallel application running on 10 CPUs, spends 15% of its total time, in sequential execution. What kind of CPU (how much faster) would we need to run this application completely sequentially, while keeping the same total time?
- iii) Why is multithreading needed? How can multiple threads run simultaneously in a single-processor system? and how can they run on multicore system? Write a program that launches 1,000 threads. Each thread adds 1 to a variable sum that initially is 0.

[3] [20 Marks]

- i) Recall that a number is prime if it is divisible only by itself and 1.
 - a) Write an algorithm uses a trial division to test the primality of a number x, i.e. whether the number x is prime or not.
 - b) Write the parallel program steps to test a big number x if prime or not. You can use any parallel programming model (language) to implement the proposed algorithm in (i-a). In your parallel program steps, you must use the multicore multithreaded.
- ii) Why use the parallel reduction pattern?
Write a parallel program to implement the Monto Carlo algorithm to approximate the value of π .

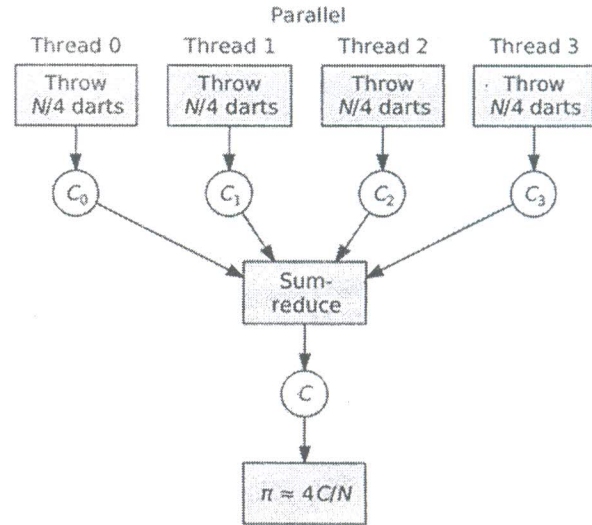
The algorithm works by taking a random sample of points (C) from a uniform distribution (N) with $0 < x, y < 1$ and determining if that point lies within the first quadrant of the unit circle centered at (0,0). If it does, that is considered a success, then

$$\text{success/total} \approx \pi/4 \text{ or } C/N \approx \pi/4$$

$$\text{or } \pi = 4C/N$$

Since the area of the first quadrant of the unit circle is $\pi/4$.

Note: In your program, you must implement the reduction operation, **Sum-reduce**, as shown in the Figure.



[4]

[20 Marks]

- i) In the parallel deep Convolutional Neural Network (CNN) if the input image is $255 \times 255 \times 3$, two filters are used of sizes 11×11 at stride 4 and 9×9 at stride 3 respectively.
- How many output tensors are generated from the 1st convolution layer? What are its sizes?
 - What are the total number of parameters?
- ii) Consider the problem of parallelizing the application of a 3×3 convolution kernel for sharpening an image. The kernel is a square matrix (3×3) with weights that are used in the calculation of the new pixel data. Convolution between a kernel K of odd size n and an image f is defined by the formula:

$$g(x, y) = \sum_{i=-n_2}^{n_2} \sum_{j=-n_2}^{n_2} k(n_2 + i, n_2 + j) f(x - i, y - j)$$

Where $n_2 = \lfloor \frac{n}{2} \rfloor$, floor function.

If, for example, a 3×3 kernel is used:

$$K = \begin{bmatrix} k_{0,0} & k_{0,1} & k_{0,2} \\ k_{1,0} & k_{1,1} & k_{1,2} \\ k_{2,0} & k_{2,1} & k_{2,2} \end{bmatrix}$$

then for each pixel at row i and column j , the new pixel value $v'_{i,j}$ resulting from the convolution is determined by the values of the pixel and its eight neighbors according to the formula:

$$\begin{aligned} v'_{i,j} = & v_{i-1,j-1} \cdot k_{2,2} + v_{i-1,j} \cdot k_{2,1} + v_{i-1,j+1} \cdot k_{2,0} \\ & + v_{i,j-1} \cdot k_{1,2} + v_{i,j} \cdot k_{1,1} + v_{i,j+1} \cdot k_{1,0} \\ & + v_{i+1,j-1} \cdot k_{0,2} + v_{i+1,j} \cdot k_{0,1} + v_{i+1,j+1} \cdot k_{0,0} \end{aligned}$$

Where v are original pixel values.

- State the steps how to implement the application (ii) in parallel using GPU
- Write the pseudocode for applying the convolution kernel to an image as stated in (ii).